

5 MOS Field-Effect Transistors (MOSFETs)

Section 5.1: Device Structure and Physical Operation

5.1

An NMOS transistor is fabricated in a $0.13\text{-}\mu\text{m}$ CMOS process with $L = 1.5L_{\min}$ and $W = 1.3\text{ }\mu\text{m}$. The process technology is specified to have $t_{ox} = 2.7\text{ nm}$, $\mu_n = 400\text{ cm}^2/\text{V}\cdot\text{s}$, and $V_m = 0.4\text{ V}$.

- (a) Find C_{ox} , k'_n , and k_n .
- (b) Find the overdrive voltage V_{OV} and the minimum value of V_{DS} required to operate the transistor in saturation at a current $I_D = 100\text{ }\mu\text{A}$. What gate-to-source voltage is required?
- (c) If V_{DS} is very small, what values of V_{OV} and V_{GS} are required to operate the MOSFET as a $2\text{-k}\Omega$ resistance? If V_{GS} is doubled, what r_{DS} results? If V_{GS} is reduced, at what value does r_{DS} become infinite?

Section 5.2: Current–Voltage Characteristics

5.2

An NMOS transistor fabricated in a $0.13\text{-}\mu\text{m}$ process has $L = 0.2\text{ }\mu\text{m}$ and $W = 2\text{ }\mu\text{m}$. The process technology has $C_{ox} = 12.8\text{ fF}/\mu\text{m}^2$, $\mu_n = 450\text{ cm}^2/\text{V}\cdot\text{s}$, and $V_m = 0.4\text{ V}$. Neglect the channel-length modulation effect.

- (a) If the transistor is to operate at the edge of the saturation region with $I_D = 100\text{ }\mu\text{A}$, find the values required of V_{GS} and V_{DS} .
- (b) If V_{GS} is kept constant at the value found in (a) while V_{DS} is changed, find I_D that results at V_{DS} equal to half the value in (a) and at V_{DS} equal to 0.1 the value in (a).
- (c) To investigate the operation of the MOSFET as a linear amplifier, let the operating point be at $V_{GS} = 0.6\text{ V}$ and $V_{DS} = 0.3\text{ V}$. Find the change in

i_D for v_{GS} changing from 0.6 V by $+10\text{ mV}$ and by -10 mV . Comment.

5.3

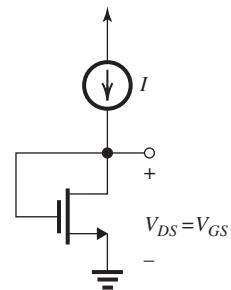


Figure 5.3.1

An NMOS transistor fabricated in a process for which the process transconductance parameter is $400\text{ }\mu\text{A/V}^2$ has its gate and drain connected together. The resulting two-terminal device is fed with a current source I as shown in Fig. 5.3.1. With $I = 40\text{ }\mu\text{A}$, the voltage across the device is measured to be 0.6 V . When I is increased to $90\text{ }\mu\text{A}$, the voltage increases to 0.7 V . Find V_t and W/L of the transistor. Ignore channel-length modulation.

5.4

An NMOS transistor for which $k_n = 4\text{ mA/V}^2$ and $V_t = 0.35\text{ V}$ is operated with $V_{GS} = V_{DS} = 0.6\text{ V}$. What current results? To what value can V_{DS} be reduced while maintaining the current unchanged? If the transistor is replaced with another fabricated in the same technology but

with twice the width, what current results? For each of the two transistors when operated at small V_{DS} , what is the range of linear resistance r_{DS} obtained when V_{GS} is varied over the range 0.5 V to 1 V? Neglect channel-length modulation.

5.5

An NMOS transistor is fabricated in a $0.13\text{-}\mu\text{m}$ process having $k'_n = 500 \mu\text{A/V}^2$, and $V'_A = 5 \text{ V}/\mu\text{m}$.

- If $L = 0.26 \mu\text{m}$ and $W = 2.6 \mu\text{m}$, find V_A and λ .
- If the device is operated at $V_{OV} = 0.2 \text{ V}$ and $V_{DS} = 0.65 \text{ V}$, find I_D .
- Find r_o at the operating point specified in (b).
- If V_{DS} is increased to 1.3 V, what is the corresponding change in I_D ? Do this two ways: using the expression for I_D and using r_o . Compare the results obtained.

5.6

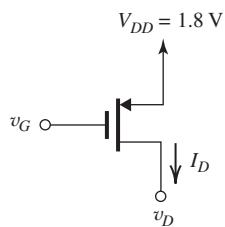


Figure 5.6.1

The PMOS transistor in Fig. 5.6.1 has $V'_{tp} = -0.5 \text{ V}$, $k'_p = 100 \mu\text{A/V}^2$, and $W/L = 10$.

- Find the range of v_G for which the transistor conducts.
- In terms of v_G , find the range of v_D for which the transistor operates in the triode region.
- In terms of v_G , find the range of v_D for which the transistor operates in saturation.
- Find the value of v_G and the range of v_D for which the transistor operates in saturation with $I_D = 20 \mu\text{A}$. Assume $\lambda = 0$.
- If $|\lambda| = 0.2 \text{ V}^{-1}$, find r_o at the operating point in (d).
- For V_{OV} equal to that in (d) and $|\lambda| = 0.2 \text{ V}^{-1}$, find the value of I_D at $V_D = 1 \text{ V}$ and at $V_D = 0 \text{ V}$. Use these values to calculate the output resistance r_o and compare the result to that found in (e).

Section 5.3: MOSFET Circuits at DC

D5.7

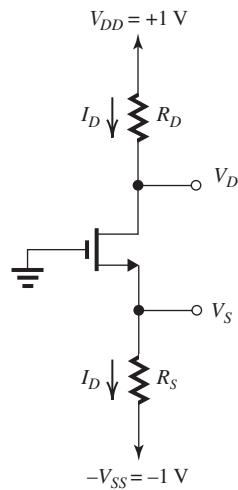


Figure 5.7.1

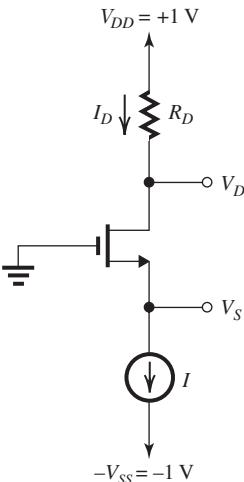
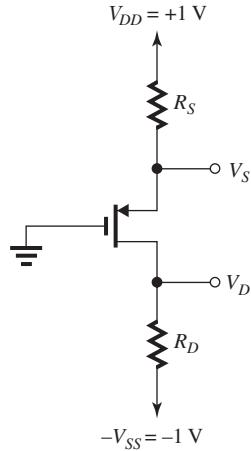


Figure 5.7.2

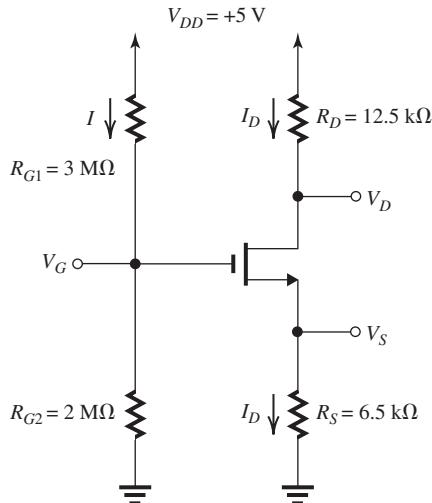
The NMOS transistor in the circuit in Fig. 5.7.1 has $V_{tn} = 0.5 \text{ V}$, $k'_n = 400 \mu\text{A/V}^2$, $W/L = 10$, and $\lambda = 0$.

- Design the circuit (i.e., find the required values for R_S and R_D) to obtain $I_D = 180 \mu\text{A}$ and $V_D = +0.5 \text{ V}$. Find the voltage V_S that results.
- If R_S is replaced with a constant-current source I , as shown in Fig. 5.7.2, what must the value of I be to obtain the same operating conditions as in (a)?
- What is the largest value to which R_D can be increased while the transistor remains in saturation?

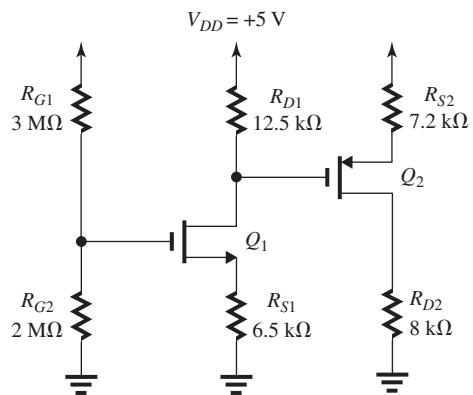
D5.8**Figure 5.8.1**

The PMOS transistor in the circuit in Fig. 5.8.1 has $V_{tp} = -0.5\text{ V}$, $k'_p = 100\text{ }\mu\text{A/V}^2$, $W/L = 20$, and $\lambda = 0$.

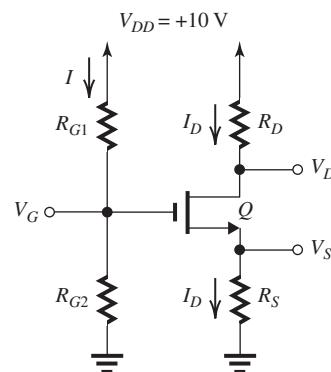
- Find R_S and R_D to obtain $I_D = 0.1\text{ mA}$ and $V_D = 0\text{ V}$.
- What is the largest R_D for which the transistor remains in saturation. At this value of R_D , what is the voltage at the drain, V_D ?

5.9**Figure 5.9.1**

The NMOS transistor in the circuit in Fig. 5.9.1 has $V_t = 0.5\text{ V}$, $k_n = 10\text{ mA/V}^2$, and $\lambda = 0$. Analyze the circuit to determine the currents through all branches and to find the voltages at all nodes.

5.10**Figure 5.10.1**

For the circuit in Fig. 5.10.1, the NMOS transistor has $V_{tn} = 0.5\text{ V}$, $k_n = 10\text{ mA/V}^2$, and $\lambda_n = 0$, and the PMOS transistor has $V_{tp} = -0.5\text{ V}$, $k_p = 12.5\text{ mA/V}^2$, and $|\lambda_p| = 0$. Observe that Q_1 and its surrounding circuit is the same as the circuit analyzed in Problem 5.9 (Fig. 5.9.1), and you may use the results found in the solution to that problem here. Analyze the circuit to determine the currents in all branches and the voltages at all nodes.

D5.11**Figure 5.11.1**

Design the circuit in Fig. 5.11.1 to obtain $I = 1\text{ }\mu\text{A}$, $I_D = 0.5\text{ mA}$, $V_S = 2\text{ V}$, and $V_D = 5\text{ V}$. The NMOS transistor has $V_t = 0.5\text{ V}$, $k_n = 4\text{ mA/V}^2$, and $\lambda = 0$.

5.12

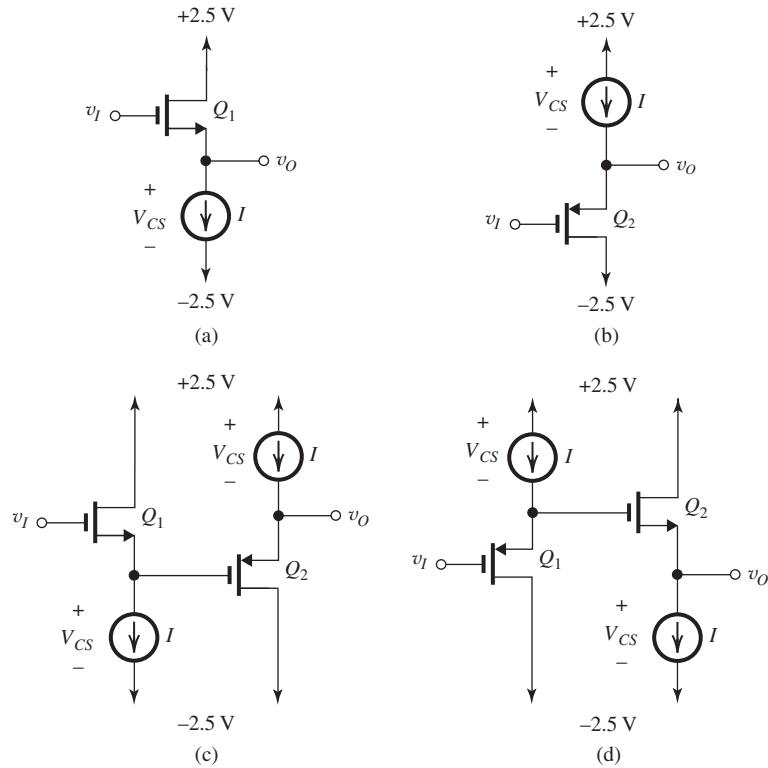


Figure 5.12.1

The transistors in the circuits of Fig. 5.12.1 have $|V_T| = 0.5\text{ V}$, $k_n = k_p = 20\text{ mA/V}^2$, and $\lambda = 0$. Also, $I = 0.9\text{ mA}$. For each circuit find v_O as a function of v_I assuming the transistors are operating

in saturation. In each case find the allowable ranges of v_O and v_I . Assume that the minimum voltage V_{CS} required across each current source is 0.3 V .

5 MOS Field-Effect Transistors (MOSFETs)

5.1

(a)

$$L = 1.5L_{\min} = 1.5 \times 0.13 = 0.195 \mu\text{m}$$

$$C_{ox} = \frac{\epsilon_{ox}}{t_{ox}}$$

where

$$\begin{aligned} \epsilon_{ox} &= 3.9 \epsilon_0 = 3.9 \times 8.854 \times 10^{-12} \\ &= 3.45 \times 10^{-11} \text{ F/m} \\ C_{ox} &= \frac{3.45 \times 10^{-11} \text{ F/m}}{2.7 \times 10^{-9} \text{ m}} \\ &= 1.28 \times 10^{-2} \text{ F/m}^2 \\ &= 1.28 \times 10^{-2} \times 10^{15} \times 10^{-12} \text{ fF}/\mu\text{m}^2 \\ &= 12.8 \text{ fF}/\mu\text{m}^2 \end{aligned}$$

$$\begin{aligned} k'_n &= \mu_n C_{ox} \\ &= 400 (\text{cm}^2/\text{V}\cdot\text{s}) \times 12.8 (\text{fF}/\mu\text{m}^2) \\ &= 400 \times 10^8 (\mu\text{m}^2/\text{V}\cdot\text{s}) \times 12.8 \times 10^{-15} (\text{F}/\mu\text{m}^2) \\ &= 512 \times 10^{-6} (\text{F}/\text{V}\cdot\text{s}) = 512 \times 10^{-6} (\text{A}/\text{V}^2) \\ &= 512 \mu\text{A}/\text{V}^2 \end{aligned}$$

$$\begin{aligned} k_n &= k'_n (W/L) \\ &= 512 \times \frac{1.3}{0.195} = 3413 \mu\text{A}/\text{V}^2 \end{aligned}$$

$$k_n = 3.413 \text{ mA/V}^2$$

(b) When the MOSFET operates in saturation, we have

$$I_D = \frac{1}{2} k_n V_{OV}^2$$

Thus,

$$\begin{aligned} 100 &= \frac{1}{2} \times 3413 \times V_{OV}^2 \\ \Rightarrow V_{OV} &= 0.24 \text{ V} \end{aligned}$$

To operate in saturation, V_{DS} must at least be equal to V_{OV} , thus

$$V_{DS\min} = 0.24 \text{ V}$$

The gate-to-source voltage is

$$V_{GS} = V_m + V_{OV} = 0.4 + 0.24 = 0.64 \text{ V}$$

(c) When v_{DS} is small,

$$i_D \simeq k_n V_{OV} v_{DS}$$

and

$$r_{DS} \equiv \frac{v_{DS}}{i_D} = 1/k_n V_{OV}$$

Thus, for $r_{DS} = 2 \text{ k}\Omega$,

$$\begin{aligned} 2 \times 10^3 &= \frac{1}{3.413 \times 10^{-3} V_{OV}} \\ \Rightarrow V_{OV} &= 0.15 \text{ V} \end{aligned}$$

and, correspondingly,

$$V_{GS} = 0.4 + 0.15 = 0.55 \text{ V}$$

If V_{GS} is doubled, we obtain

$$V_{GS} = 2 \times 0.55 = 1.1 \text{ V}$$

and

$$V_{OV} = 1.1 - 0.4 = 0.7 \text{ V}$$

Thus, correspondingly, r_{DS} becomes

$$\begin{aligned} r_{DS} &= \frac{1}{k_n V_{OV}} = \frac{1}{3.413 \times 10^{-3} \times 0.7} \\ &= 418.6 \Omega \end{aligned}$$

As V_{GS} is reduced, r_{DS} increases, becoming infinite when the channel disappears, which occurs as V_{OV} reaches zero or, correspondingly,

$$V_{GS} = V_{tn} = 0.4 \text{ V}$$

5.2

(a) When the transistor operates in saturation, we obtain

$$I_D = \frac{1}{2} \mu_n C_{ox} \left(\frac{W}{L} \right) V_{OV}^2$$

where

$$\begin{aligned} \mu_n C_{ox} &= 450 \text{ (cm}^2/\text{V}\cdot\text{s}) \times 12.8 \text{ (fF}/\mu\text{m}^2\text{)} \\ &= 450 \times 10^8 \text{ (\mu m}^2/\text{V}\cdot\text{s}) \times 12.8 \times 10^{-15} \text{ (F}/\mu\text{m}^2\text{)} \\ &= 576 \times 10^{-6} \text{ (F/V}\cdot\text{s)} \\ &= 576 \mu\text{A/V}^2 \end{aligned}$$

To obtain $I_D = 100 \mu\text{A}$, V_{OV} can be found from

$$\begin{aligned} 100 &= \frac{1}{2} \times 576 \times \frac{2 \mu\text{m}}{0.2 \mu\text{m}} \times V_{OV}^2 \\ \Rightarrow V_{OV} &= 0.186 \text{ V} \end{aligned}$$

Correspondingly,

$$V_{GS} = V_{tn} + V_{OV} = 0.4 + 0.186 = 0.586 \text{ V}$$

At the edge of saturation,

$$V_{DS} = V_{DS\min} = V_{OV} = 0.186 \text{ V}$$

(b) If V_{DS} is lowered below $V_{DS\min}$, the transistor operates in the triode region, thus

$$\begin{aligned} i_D &= \mu_n C_{ox} \left(\frac{W}{L} \right) \left[(V_{GS} - V_{tn}) v_{DS} - \frac{1}{2} v_{DS}^2 \right] \\ &= 576 \times \frac{2}{0.2} (0.186 v_{DS} - 0.5 v_{DS}^2) \end{aligned}$$

For

$$v_{DS} = 0.5 V_{DS\min} = 0.5 \times 0.186 = 0.093 \text{ V}$$

we obtain

$$\begin{aligned} i_D &= 576 \times 10 (0.186 \times 0.093 - 0.5 \times 0.093^2) \\ &= 74.7 \mu\text{A} \end{aligned}$$

For

$$v_{DS} = 0.1 V_{DS\min} = 0.1 \times 0.186 = 0.0186 \text{ V}$$

we get

$$\begin{aligned} i_D &= 576 \times 10 (0.186 \times 0.0186 - 0.5 \times 0.0186^2) \\ &= 18.9 \mu\text{A} \end{aligned}$$

(c) For $V_{GS} = 0.6 \text{ V}$ (i.e., $V_{OV} = 0.2 \text{ V}$) and $V_{DS} = 0.3 \text{ V}$, the MOSFET will be operating in saturation with

$$\begin{aligned} I_D &= \frac{1}{2} \mu_n C_{ox} \left(\frac{W}{L} \right) V_{OV}^2 \\ &= \frac{1}{2} \times 576 \times \frac{2}{0.2} \times 0.2^2 \\ &= 115.2 \mu\text{A} \end{aligned}$$

Now, if v_{GS} is increased by a 10-mV increment, then

$$v_{GS} = 0.6 + 0.010 = 0.610 \text{ V}$$

and the current becomes

$$\begin{aligned} i_D &= \frac{1}{2} \times 576 \times \frac{2}{0.2} \times (0.610 - 0.4)^2 \\ &= 127 \mu\text{A} \end{aligned}$$

Thus, i_D increases by an increment

$$\Delta i_D = 127 - 115.2 = 11.8 \mu\text{A}$$

If v_{GS} is decreased by 10 mV, we obtain

$$v_{GS} = 0.6 - 0.010 = 0.590 \text{ V}$$

and the current becomes

$$\begin{aligned} i_D &= \frac{1}{2} \times 576 \times \frac{2}{0.2} \times (0.590 - 0.4)^2 \\ &= 104 \mu\text{A} \end{aligned}$$

Thus, the change in i_D is

$$\Delta i_D = 104 - 115.2 = -11.2 \mu\text{A}$$

Observe that the incremental changes in i_D are almost equal, indicating that the operation is almost linear. Linearity improves if the incremental changes in v_{GS} are made smaller. (For instance, try $\Delta v_{GS} = \pm 5 \text{ mV}$.)

5.3

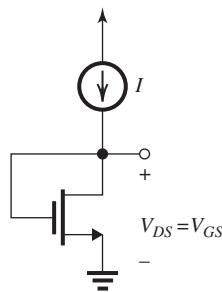


Figure 5.3.1

Refer to Fig. 5.3.1 and observe that since $V_{DS} = V_{GS} = V_t + V_{OV}$, we have

$$V_{DS} > V_{OV}$$

and thus the MOSFET is operating in the saturation region. Thus, ignoring channel-length modulation, we can write

$$I_D = \frac{1}{2} k_n \frac{W}{L} (V_{GS} - V_t)^2$$

Substituting the given data, we obtain

$$40 = \frac{1}{2} \times 400 \times \left(\frac{W}{L} \right) (0.6 - V_t)^2 \quad (1)$$

and

$$90 = \frac{1}{2} \times 400 \times \left(\frac{W}{L} \right) (0.7 - V_t)^2 \quad (2)$$

Dividing Eq. (2) by Eq. (1), we obtain

$$\begin{aligned} \frac{9}{4} &= \frac{(0.7 - V_t)^2}{(0.6 - V_t)^2} \\ \Rightarrow \frac{3}{2} &= \frac{0.7 - V_t}{0.6 - V_t} \end{aligned}$$

which results in

$$V_t = 0.4 \text{ V}$$

Substituting for V_t into Eq. (1) gives

$$\begin{aligned} 40 &= 200 \times \left(\frac{W}{L} \right) \times 0.04 \\ \Rightarrow \frac{W}{L} &= 5 \end{aligned}$$

5.4

Operation with $V_{DS} = V_{GS} = V_t + V_{OV}$ means $V_{DS} > V_{OV}$ and thus the MOSFET is in the saturation region. Thus, neglecting channel-length modulation, we can write for I_D ,

$$\begin{aligned} I_D &= \frac{1}{2} k_n (V_{GS} - V_t)^2 \\ &= \frac{1}{2} \times 4 \times (0.6 - 0.35)^2 \\ &= 0.125 \text{ mA} \end{aligned}$$

The voltage V_{DS} can be reduced to a value equal to V_{OV} while the MOSFET remains in the saturation region, that is,

$$V_{DS\min} = 0.6 - 0.35 = 0.25 \text{ V}$$

A transistor having twice the value of W will have twice the value of k_n and thus the current will be twice as large, that is,

$$I_D = 2 \times 0.125 = 0.25 \text{ mA}$$

The linear resistance r_{DS} is given by

$$r_{DS} = \frac{1}{k_n (V_{GS} - V_t)}$$

With $V_t = 0.35 \text{ V}$ and with V_{GS} varying over the range 0.5 V to 1 V , r_{DS} will vary over the range

$$r_{DS} = \frac{1}{0.15 k_n} \text{ to } \frac{1}{0.65 k_n}$$

For the first device with $k_n = 4 \text{ mA/V}$, r_{DS} will vary over the range

$$r_{DS} = \frac{1}{0.15 \times 4} = 1.67 \text{ k}\Omega$$

to

$$r_{DS} = \frac{1}{0.65 \times 4} = 0.38 \text{ k}\Omega$$

The wider device has $k_n = 8 \text{ mA/V}$ and thus its r_{DS} will vary over the range

$$r_{DS} = 0.833 \text{ k}\Omega \text{ to } 0.192 \text{ k}\Omega$$

5.5

(a)

$$V_A = V'_A L = 5 \times 0.26 = 1.3 \text{ V}$$

$$\lambda = \frac{1}{V_A} = \frac{1}{1.3} = 0.77 \text{ V}^{-1}$$

(b) Since $V_{DS} = 0.65 \text{ V}$ is greater than V_{OV} , the NMOS transistor is operating in saturation. Thus,

$$\begin{aligned} I_D &= \frac{1}{2} k'_n \left(\frac{W}{L} \right) V_{OV}^2 (1 + \lambda V_{DS}) \\ &= \frac{1}{2} \times 500 \times \frac{2.6}{0.26} \times 0.2^2 \times (1 + 0.77 \times 0.65) \\ &= 150 \mu\text{A} \end{aligned}$$

(c)

$$r_o = \frac{V_A}{I'_D}$$

where I'_D is the drain current without taking channel-length modulation into account, thus

$$\begin{aligned} I'_D &= \frac{1}{2} k'_n \left(\frac{W}{L} \right) V_{OV}^2 \\ &= \frac{1}{2} \times 500 \times \frac{2.6}{0.26} \times 0.2^2 \\ &= 100 \mu\text{A} \end{aligned}$$

Hence,

$$r_o = \frac{1.3 \text{ V}}{100 \mu\text{A}} = \frac{1.3 \text{ V}}{0.1 \text{ mA}} = 13 \text{ k}\Omega$$

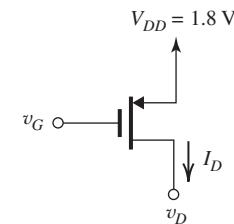
(d) If V_{DS} is increased to 1.3 V, I_D becomes

$$\begin{aligned} I_D &= \frac{1}{2} \times 500 \times \frac{2.6}{0.26} \times 0.2^2 (1 + 0.77 \times 1.3) \\ &= 200 \mu\text{A} \end{aligned}$$

That is, I_D increases by 50 μA . Alternatively, we can use r_o to determine the increase in I_D as

$$\begin{aligned} \Delta I_D &= \frac{\Delta V_{DS}}{r_o} \\ &= \frac{0.65 \text{ V}}{13 \text{ k}\Omega} = 0.05 \text{ mA} = 50 \mu\text{A} \end{aligned}$$

which is identical to the result obtained directly.

5.6**Figure 5.6.1**

$$V_{tp} = -0.5 \text{ V}, \quad k'_p = 100 \mu\text{A/V}^2$$

$$W/L = 10$$

(a) For the transistor to conduct, v_G must be lower than v_S by at least $|V_{tp}|$, that is, by 0.5 V. Thus, the transistor conducts for $v_G \leq 1.8 - 0.5$, or $v_G \leq 1.3 \text{ V}$.

(b) For the transistor to operate in the triode region, the drain voltage must be higher than the gate voltage by at least $|V_{tp}|$ volts, thus

$$v_D \geq v_G + 0.5 \text{ V}$$

(c) For the transistor to operate in the saturation region, the drain voltage cannot exceed the gate voltage by more than $|V_{tp}|$, that is,

$$v_D \leq v_G + 0.5 \text{ V}$$

(d) When the transistor is operating in saturation, we obtain

$$I_D = \frac{1}{2} k'_p \left(\frac{W}{L} \right) |V_{OV}|^2$$

Substituting the given values, we obtain

$$\begin{aligned} 20 &= \frac{1}{2} \times 100 \times 10 |V_{OV}|^2 \\ \Rightarrow |V_{OV}| &= 0.2 \text{ V} \end{aligned}$$

which is obtained when

$$\begin{aligned} v_G &= V_{DD} - V_{SG} \\ &= 1.8 - (|V_{tp}| + |V_{OV}|) \\ &= 1.8 - (0.5 + 0.2) = 1.1 \text{ V} \end{aligned}$$

For this value of v_G , the range that v_D is allowed to have while the transistor remains in saturation is

$$v_D \leq v_G + |V_{tp}|$$

that is,

5.7

$$v_D \leq 1.6 \text{ V}$$

(e)

$$r_o = \frac{|V_A|}{I'_D} = \frac{1}{|\lambda| I'_D}$$

where I'_D is the value of I_D without channel-length modulation taken into account, that is,

$$\begin{aligned} I'_D &= \frac{1}{2} k'_p \left(\frac{W}{L} \right) |V_{OV}|^2 \\ &= \frac{1}{2} \times 100 \times 10 \times 0.2^2 = 20 \mu\text{A} \end{aligned}$$

Thus,

$$r_o = \frac{1}{0.2 \times 20} = 0.25 \text{ M}\Omega$$

(f)

$$I_D = \frac{1}{2} k'_p \left(\frac{W}{L} \right) V_{OV}^2 (1 + |\lambda| V_{SD})$$

At $V_D = 1 \text{ V}$, we have $V_{SD} = 1.8 - 1 = 0.8 \text{ V}$, and

$$\begin{aligned} I_D &= \frac{1}{2} \times 100 \times 10 \times 0.2^2 (1 + 0.2 \times 0.8) = \\ &= 23.2 \mu\text{A}. \end{aligned}$$

At $V_D = 0 \text{ V}$, we get $V_{SD} = 1.8 - 0 = 1.8 \text{ V}$, and

$$I_D = \frac{1}{2} \times 100 \times 10 \times 0.2^2 (1 + 0.2 \times 1.8) = 27.2 \mu\text{A}$$

Thus, for

$$\Delta V_{SD} = 1.8 - 0.8 = 1 \text{ V},$$

the current changes by

$$\Delta I_D = 27.2 - 23.2 = 4 \mu\text{A}$$

indicating that the output resistance r_o is

$$r_o = \frac{\Delta V_D}{\Delta I_D} = \frac{1 \text{ V}}{4 \mu\text{A}} = 0.25 \text{ M}\Omega$$

which is the same value found in (e).

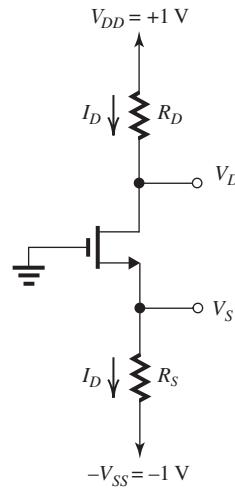


Figure 5.7.1

(a) Refer to the circuit in Fig. 5.7.1. For $V_D = +0.5 \text{ V}$, the transistor is operating in saturation since $V_D > V_G$. Thus,

$$I_D = \frac{1}{2} k'_n \left(\frac{W}{L} \right) V_{OV}^2$$

where we have utilized the given information that $\lambda = 0$. To obtain $I_D = 180 \mu\text{A}$, the required V_{OV} can be found from

$$\begin{aligned} 180 &= \frac{1}{2} \times 400 \times 10 V_{OV}^2 \\ \Rightarrow V_{OV} &= 0.3 \text{ V} \end{aligned}$$

The value of V_{GS} can be found as

$$V_{GS} = V_{in} + V_{OV} = 0.5 + 0.3 = 0.8 \text{ V}$$

from which V_S can be determined as

$$V_S = V_G - V_{GS} = 0 - 0.8 = -0.8 \text{ V}$$

The required value of R_S can now be found from

$$\begin{aligned} R_S &= \frac{V_S - (-V_{SS})}{I_D} \\ &= \frac{-0.8 - (-1)}{180 \mu\text{A}} = \frac{0.2 \text{ V}}{0.18 \text{ mA}} = 1.11 \text{ k}\Omega \end{aligned}$$

Finally, the value of R_D can be found from

$$\begin{aligned} R_D &= \frac{V_{DD} - V_D}{I_D} \\ &= \frac{1 - 0.5}{0.18 \text{ mA}} = 2.78 \text{ k}\Omega \end{aligned}$$

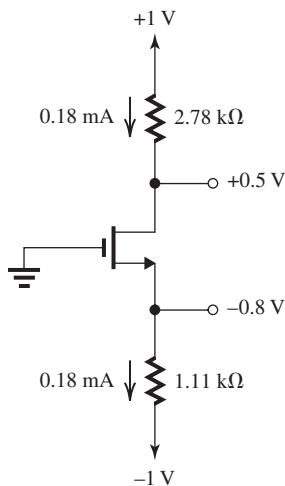


Figure 5.7.3

Figure 5.7.3 shows the designed circuit with the component values and the values of current and voltages.

(b) If R_S is replaced by a constant-current source I , as shown in Fig. 5.7.2, the value of I must be equal to the desired value of I_D , that is, $180 \mu\text{A}$ or 0.18 mA .

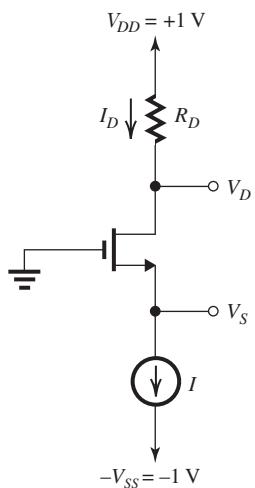


Figure 5.7.2

(c) Refer to Fig. 5.7.1. As R_D is increased, V_D decreases as

$$\begin{aligned} V_D &= 1 - I_D R_D \\ &= 1 - 0.18 R_D \end{aligned}$$

Eventually, V_D falls below V_G by V_{th} at which point the transistor leaves the saturation region and enters the triode region. This occurs at

$$V_D = V_G - V_{th} = 0 - 0.5 = -0.5 \text{ V}$$

The corresponding value of R_D can be found from

$$\begin{aligned} -0.5 &= 1 - 0.18 \times R_D \\ \Rightarrow R_D &= 8.33 \text{ k}\Omega \end{aligned}$$

5.8

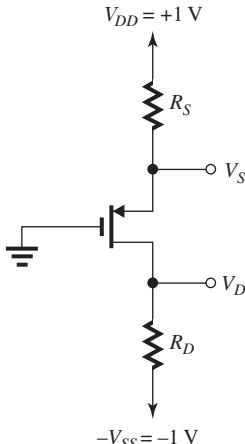


Figure 5.8.1

(a) With $V_D = 0 \text{ V}$, the transistor will be operating in the saturation region since $V_D = V_G$. Thus,

$$I_D = \frac{1}{2} k'_p \left(\frac{W}{L} \right) |V_{OV}|^2$$

where we have taken into account that $\lambda = 0$ as stated. To obtain $I_D = 0.1 \text{ mA} = 100 \mu\text{A}$, the required value of $|V_{OV}|$ can be found as follows:

$$\begin{aligned} 100 &= \frac{1}{2} \times 100 \times 20 |V_{OV}|^2 \\ \Rightarrow |V_{OV}| &= 0.316 \text{ V} \end{aligned}$$

The value of V_{SG} can now be found as

$$V_{SG} = |V_{tp}| + |V_{OV}| = 0.5 + 0.316 = 0.816 \text{ V}$$

Thus,

$$V_S = V_{SG} = 0.816 \text{ V}$$

The required value of R_S can be determined from

$$\begin{aligned} R_S &= \frac{V_{DD} - V_S}{I_D} \\ &= \frac{1 - 0.816}{0.1} = 1.84 \text{ k}\Omega \end{aligned}$$

Finally, the required value of R_D can be found from

$$\begin{aligned} R_D &= \frac{V_D - (-V_{SS})}{I_D} \\ &= \frac{0 - (-1)}{0.1} = 10 \text{ k}\Omega \end{aligned}$$

The designed circuit with component values and current and voltage values is shown in Figure 5.8.2. The reader can check the calculations directly on the circuit diagram.

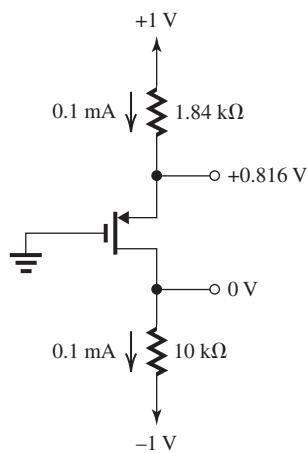


Figure 5.8.2

(b) Refer to Figure 5.8.1. The transistor remains in saturation as long as V_D does not increase above V_G by more than $|V_{tp}|$. Since $V_G = 0$ and $|V_{tp}| = 0.5 \text{ V}$, the maximum allowable value of V_D is

$$V_{D\max} = +0.5 \text{ V}$$

To obtain this value of V_D , R_D must be increased to

$$R_D = \frac{V_{D\max} - (-1)}{0.1 \text{ mA}} = \frac{0.5 + 1}{0.1} = 15 \text{ k}\Omega$$

5.9

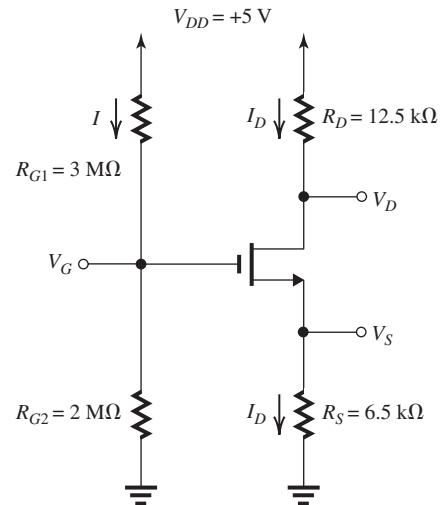


Figure 5.9.1

The current I through the voltage divider $R_{G1}-R_{G2}$ can be found as

$$\begin{aligned} I &= \frac{V_{DD}}{R_{G1} + R_{G2}} \\ &= \frac{5 \text{ V}}{3 \text{ M}\Omega + 2 \text{ M}\Omega} = \frac{5 \text{ V}}{5 \text{ M}\Omega} = 1 \mu\text{A} \end{aligned}$$

The voltage V_G at the gate can now be found as

$$V_G = IR_{G2} = 1 \mu\text{A} \times 2 \text{ M}\Omega = 2 \text{ V}$$

The voltage V_S is given by

$$V_S = V_G - V_{GS} = V_G - (V_t + V_{OV})$$

$$= 2 - (0.5 + V_{OV})$$

$$V_S = 1.5 - V_{OV} \quad (1)$$

But V_S can be expressed in terms of I_D as

$$V_S = I_D R_S = I_D \times 6.5 = 6.5 I_D$$

Thus,

$$6.5 I_D = 1.5 - V_{OV} \quad (2)$$

We do not know whether the transistor is operating in the saturation region or in the triode region. Therefore, we must make an assumption about the region of operation, complete the analysis, and then use the results obtained to check the validity of our assumption. If our assumption proves valid, our work is done. Otherwise, we must redo the analysis assuming the other mode of operation. Since the $i-v$ relationships that describe the saturation-region operation are simpler than those that apply in the triode region, we normally assume operation in the saturation region, unless of course there is an indication of triode-mode operation.

Assuming that the transistor in the circuit of Figure 5.9.1 is operating in saturation, we can write

$$I_D = \frac{1}{2} k_n V_{OV}^2 = \frac{1}{2} \times 10 V_{OV}^2$$

$$I_D = 5 V_{OV}^2 \quad (3)$$

Substituting for I_D from Eq. (3) into Eq. (2) gives

$$6.5 \times 5 V_{OV}^2 = 1.5 - V_{OV}$$

which can be rearranged into the form

$$32.5 V_{OV}^2 + V_{OV} - 1.5 = 0$$

Solving this quadratic equation yields

$$V_{OV} = 0.2 \text{ V or } -0.23 \text{ V}$$

Obviously, the negative value is physically meaningless and can be discarded. Thus,

$$V_{OV} = 0.2 \text{ V}$$

and

$$I_D = 5 V_{OV}^2 = 5 \times 0.2^2 = 0.2 \text{ mA}$$

We are now ready to check the validity of our assumption of saturation mode operation. Referring to the circuit in Figure 5.9.1, we can find the voltage V_D as follows:

$$V_D = V_{DD} - I_D R_D$$

$$= 5 - 0.2 \times 12.5 = 2.5 \text{ V}$$

which is greater than V_G (2 V), confirming that the transistor is operating in saturation, as assumed. Figure 5.9.2 shows the circuit together with the values of all node voltages and branch currents.

The reader is encouraged to check their results by doing a few calculations directly on the circuit.

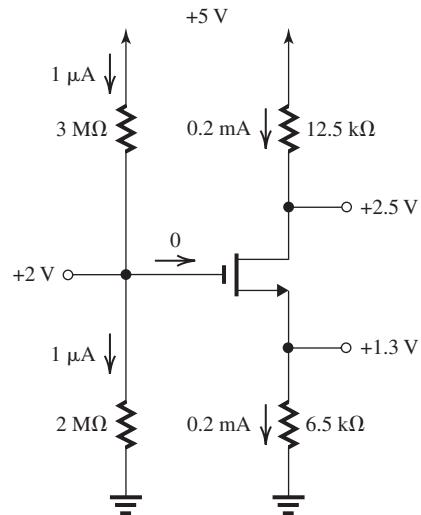


Figure 5.9.2

5.10

From Fig. 5.10.1 in the problem statement we observe that transistor Q_1 together with its associated resistors is an identical circuit to that analyzed in the solution to Problem 5.9 (see Fig. 5.9.1). Since the gate terminal of Q_2 draws zero current, transistor Q_2 together with its associated resistances do **not** change the currents and voltages in Q_1 and its associated resistances. Thus, we need to only concern ourselves with the analysis of the part of the circuit shown in Figure 5.10.2, where V_{GS} is found from

$$V_{G2} = V_{D1} = 2.5 \text{ V}$$

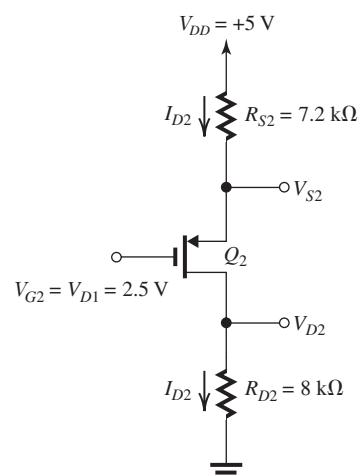


Figure 5.10.2

Since we do not know whether Q_2 is operating in saturation or in the triode region, we shall assume saturation-mode operation and, of course, we will have to check the validity of this assumption. We can now write

$$\begin{aligned} I_{D2} &= \frac{1}{2} k_p |V_{OV2}|^2 \\ &= \frac{1}{2} \times 12.5 |V_{OV2}|^2 \end{aligned}$$

Thus,

$$I_{D2} = 6.25 |V_{OV2}|^2, \text{ mA} \quad (1)$$

Another relationship between I_{D2} and $|V_{OV2}|$ can be obtained as follows:

$$\begin{aligned} V_{S2} &= V_{G2} + V_{SG2} \\ &= V_{G2} + (|V_{tp}| + |V_{OV2}|) \\ &= 2.5 + 0.5 + |V_{OV2}| \\ &= 3 + |V_{OV2}| \end{aligned}$$

But

$$\begin{aligned} I_{D2} &= \frac{V_{DD} - V_{S2}}{R_{S2}} \\ &= \frac{5 - (3 + |V_{OV2}|)}{7.2} \\ I_{D2} &= \frac{2 - |V_{OV2}|}{7.2}, \text{ mA} \quad (2) \end{aligned}$$

Equating I_{D2} from Eqs. (1) and (2) results in

$$6.25 |V_{OV2}|^2 = \frac{2 - |V_{OV2}|}{7.2}$$

which can be rearranged into the form

$$45 |V_{OV2}|^2 + |V_{OV2}| - 2 = 0$$

This quadratic equation can be solved to obtain

$$|V_{OV2}| = 0.2 \text{ V or } -0.22 \text{ V}$$

Obviously, the negative solution is physically meaningless, thus

$$|V_{OV2}| = 0.2 \text{ V}$$

and

$$I_{D2} = 6.25 \times 0.2^2 = 0.25 \text{ mA}$$

We are now ready to check the validity of our assumption of saturation-mode operation. We can do this by finding V_{D2} :

$$V_{D2} = I_{D2} R_{D2} = 0.25 \times 8 = 2 \text{ V}$$

which is lower than the voltage at the gate ($V_{G2} = 2.5 \text{ V}$), confirming saturation-mode operation. The voltage V_{S2} can be found as

$$V_{S2} = V_{DD} - I_{D2} R_{S2} = 5 - 0.25 \times 7.2 = +3.2 \text{ V}$$

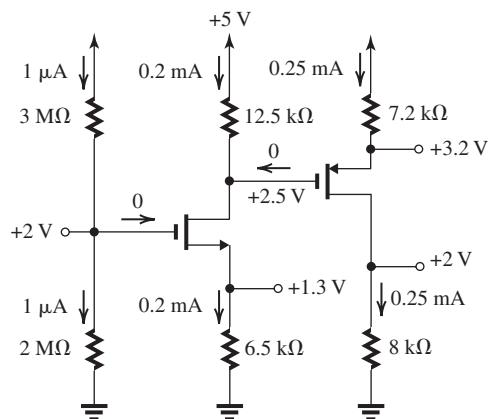


Figure 5.10.3

Finally, Fig. 5.10.3 shows the complete circuit with all currents and voltages. The values associated with Q_1 are those obtained in the solution for Problem 5.9. The reader is urged to make a few quick checks on the results displayed in Fig. 5.10.3.

5.11

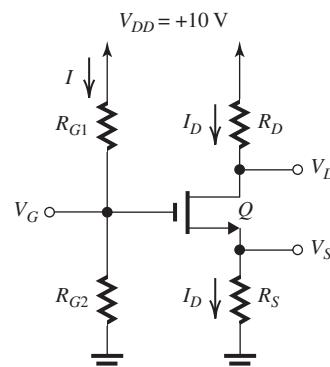


Figure 5.11.1

Refer to Fig. 5.11.1. We assume that the transistor is operating in the saturation mode, thus

$$I_D = \frac{1}{2} k_n V_{OV}^2$$

where we have taken account of the stated value $\lambda = 0$. To obtain $I_D = 0.5$ mA, the required value of V_{OV} can be found from

$$\begin{aligned} 0.5 &= \frac{1}{2} \times 4V_{OV}^2 \\ \Rightarrow V_{OV} &= 0.5 \text{ V} \end{aligned}$$

Now, since

$$V_{DS} = V_D - V_S = 5 - 2 = 3 \text{ V}$$

is greater than V_{OV} , the MOSFET is operating in saturation, as assumed. The required value of R_S can be determined as follows:

$$R_S = \frac{V_S}{I_D} = \frac{2}{0.5} = 4 \text{ k}\Omega$$

and the required value of R_D can be determined as follows:

$$R_D = \frac{V_{DD} - V_D}{I_D} = \frac{10 - 5}{0.5} = 10 \text{ k}\Omega$$

The voltage at the gate V_G is found as

$$V_G = V_{GS} + V_S$$

where

$$V_{GS} = V_t + V_{OV} = 0.5 + 0.5 = 1 \text{ V}$$

Thus,

$$V_G = 1 + 2 = 3 \text{ V}$$

The resistance R_{G1} can be found as follows:

$$R_{G1} = \frac{V_{DD} - V_G}{I} = \frac{10 - 3}{1 \mu\text{A}} = 7 \text{ M}\Omega$$

and, finally, R_{G2} can be found as

$$R_{G2} = \frac{V_G}{I} = \frac{3 \text{ V}}{1 \mu\text{A}} = 3 \text{ M}\Omega$$

5.12

(a)

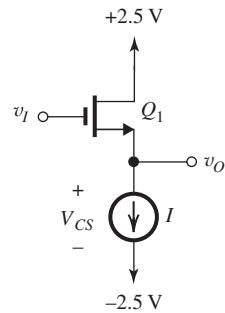


Figure 5.12.1(a)

$$v_O = v_I - V_{GS}$$

where

$$V_{GS} = V_t + V_{OV}$$

and V_{OV} can be found from

$$I_D = I = \frac{1}{2} k_n V_{OV}^2$$

Thus,

$$0.9 = \frac{1}{2} \times 20V_{OV}^2$$

$$\Rightarrow V_{OV} = 0.3 \text{ V}$$

and

$$V_{GS} = 0.5 + 0.3 = 0.8 \text{ V}$$

Thus,

$$v_O = v_I - 0.8 \quad (1)$$

The highest value that v_O can have while the transistor remains in saturation is limited by the need to keep v_{DS} at least equal to V_{OV} , thus

$$v_{O\max} = 2.5 - V_{OV} = 2.2 \text{ V}$$

The lowest value that v_O can have is limited by the need to keep the voltage across the current source V_{CS} at least equal to 0.3 V, thus

$$v_{O\min} = -2.5 + 0.3 = -2.2 \text{ V}$$

Thus, the allowable range of v_O is

$$-2.2 \text{ V} \leq v_O \leq +2.2 \text{ V}$$

and the corresponding allowable range of v_I can be found using Eq. (1) as

$$-1.4 \text{ V} \leq v_I \leq +3 \text{ V}$$

(b)

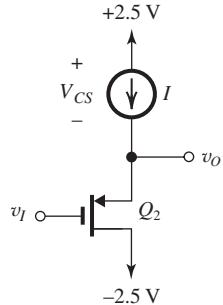


Figure 5.12.1(b)

$$v_O = v_I + V_{SG}$$

where

$$V_{SG} = |V_I| + |V_{OV}|$$

and $|V_{OV}|$ can be found from

$$\begin{aligned} I_D &= I = \frac{1}{2} k_p |V_{OV}|^2 \\ 0.9 &= \frac{1}{2} \times 20 |V_{OV}|^2 \\ \Rightarrow |V_{OV}| &= 0.3 \text{ V} \end{aligned}$$

Thus,

$$V_{SG} = 0.5 + 0.3 = 0.8 \text{ V}$$

and,

$$v_O = v_I + 0.8 \quad (2)$$

The highest value that v_O can have is limited by the need to keep the voltage V_{CS} across the current source to at least 0.3 V, thus

$$v_{O\max} = 2.5 - 0.3 = 2.2 \text{ V}$$

The lowest value that v_O can have is limited by the need to keep the voltage v_{SD} to a value at least equal to $|V_{OV}|$, thus

$$v_{O\min} = -2.5 + 0.3 = -2.2 \text{ V}$$

Thus, the allowable range of v_O is

$$-2.2 \text{ V} \leq v_O \leq +2.2 \text{ V}$$

The corresponding range of v_I can be determined using Eq. (2) as

$$-3 \text{ V} \leq v_I \leq +1.4 \text{ V}$$

(c)

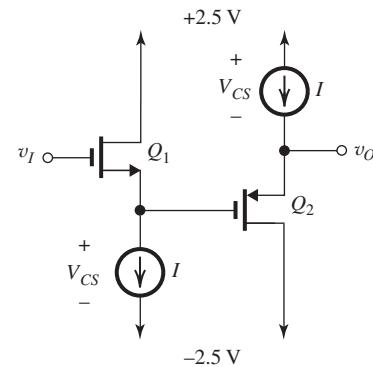


Figure 5.12.1(c)

From the results of (a) and (b), we know that

$$V_{GS1} = V_{SG2} = 0.8 \text{ V}$$

The voltage v_O can be found as follows:

$$\begin{aligned} v_O &= v_I - V_{GS1} + V_{GS2} \\ &= v_I - 0.8 + 0.8 \end{aligned}$$

Thus,

$$v_O = v_I \quad (3)$$

The highest value of v_O is determined by the need to keep the voltage V_{CS} across the current source I of Q_2 at least equal to 0.3 V. Thus,

$$v_{O\max} = 2.5 - 0.3 = +2.2 \text{ V}$$

At this value, the voltage at the source of Q_1 is

$$v_{S1} = 2.2 - 0.8 = +1.4 \text{ V}$$

which is an allowed value as we determined in (a) above.

The lowest value of v_O can be determined by the need to maintain a minimum v_{SD} across Q_2 of value equal to $|V_{OV}| = 0.3$ V. This would imply that v_O can be as low as $-2.5 + 0.3 = -2.2$ V. However, $v_O = -2.2$ V would require v_{S1} to be $v_{S1} = -2.2 - V_{SG} = -2.2 - 0.8 = -3$ V, which is **not** within the allowable range for v_{S1} [see (a) above]. It follows that the lowest allowable value of v_O is determined by the lowest allowable value at the source of Q_1 :

$$\begin{aligned} v_{O\min} &= v_{S1\min} + V_{SG} \\ &= -2.2 + 0.8 \\ &= -1.4 \text{ V} \end{aligned}$$

Thus, the allowable range of v_O is

$$-1.4 \text{ V} \leq v_O \leq +2.2 \text{ V}$$

and using Eq. (3), the allowable range of v_I can be found as

$$-1.4 \text{ V} \leq v_I \leq 2.2 \text{ V}$$

(d)

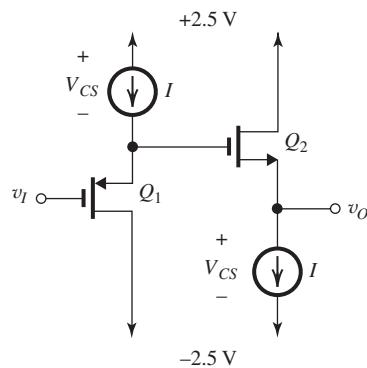


Figure 5.12.1(d)

Following a procedure identical to that we used for (c) above, we can show that here

$$v_O = v_I \quad (4)$$

and that the allowable range at the output is

$$-2.2 \text{ V} \leq v_O \leq +1.4 \text{ V}$$

and at the input

$$-2.2 \text{ V} \leq v_I \leq +1.4 \text{ V}$$